PDL with Negation of Atomic Programs

Carsten Lutz[1] and Dirk Walther[2]

[1] Inst. for Theoretical Computer Science
TU Dresden, Germany
lutz@tcs.inf.tu-dresden.de
[2] Dept. of Computer Science
University of Liverpool, UK
dwalther@csc.liv.ac.uk

Abstract. Propositional dynamic logic (PDL) is one of the most successful variants of modal logic. To make it even more useful for applications, many extensions of PDL have been considered in the literature. A very natural and useful such extension is with negation of programs. Unfortunately, as long-known, reasoning with the resulting logic is undecidable. In this paper, we consider the extension of PDL with negation of atomic programs, only. We argue that this logic is still useful, e.g. in the context of description logics, and prove that satisfiability is decidable and ExpTime-complete using an approach based on Büchi tree automata.

1 Introduction

Propositional dynamic logic (PDL) is a variant of propositional modal logic that has been developed in the late seventies as a tool for reasoning about programs [1, 2,3,4,5]. Since then, PDL was used rather successfully in a large number of application areas such as reasoning about knowledge [6], reasoning about actions [7, 8], description logics [9], and others. Starting almost with its invention around 1979 [3], many extensions of PDL have been proposed with the goal to enhance the expressive power and make PDL even more applicable; see e.g. [10,4,5]. Some of these extensions are tailored toward specific application areas, such as the *halt* predicate that allows to state termination in the context of reasoning about programs [11]. The majority of proposed extensions, however, is of a general nature and has been employed in many different application areas—for instance, the extension of PDL with the widely applied converse operator [12].

Among the general purpose extensions of PDL, two of the most obvious ones are the addition of program intersection "$\cap$" and of program negation "$\neg$" [13, 4,5]. Since PDL already provides for program union "$\cup$", the latter is more general than the former: $\alpha \cap \beta$ can simply be expressed as $\neg(\neg\alpha \cup \neg\beta)$. The main obstacle for using these two extensions in practical applications is that they are problematic w.r.t. their computational properties: first, adding intersection destroys many of the nice model-theoretic properties of PDL. The only known algorithm for reasoning in the resulting logic PDL$^\cap$ is the quite intricate one given in [13]. Up to now, it is unknown whether the provided 2-ExpTime upper bound is tight—in contrast to ExpTime-complete reasoning in PDL. Second,

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the situation with PDL extended with negation ($\mathrm{PDL}^{\neg}$) is even worse: it was observed quite early in 1984 that reasoning in $\mathrm{PDL}^{\neg}$ is undecidable [4].

This undecidability was often regretted [4,10,14], in particular since reasoning in $\mathrm{PDL}^{\neg}$ would be quite interesting for a number of application areas. To illustrate the usefulness of this logic, let us give three examples of its expressive power: first, it was already noted that negation can be employed to express intersection. Intersection, in turn, is very useful for reasoning about programs since it allows to capture the parallel execution of programs. Second, program negation allows to express the universal modality $\Box_U \varphi$ by writing $[a]\varphi \wedge [\neg a]\varphi$, with a an arbitrary atomic program. The universal modality is a very useful extension of modal logics that comes handy in many applications; see e.g. [15]. Third, program negation can be used to express the window operator $\boxplus_a$ [16, 17,18], whose semantics is as follows: $\boxplus_a \varphi$ holds at a world w iff φ holding at a world w' implies that w' is a-accessible from w. In $\mathrm{PDL}^{\neg}$, we can thus just write $[\neg a]\neg\varphi$ instead of $\boxplus_a \varphi$. The window operator can be viewed as expressing sufficiency in contrast to the standard box operator of modal logic, which expresses necessity. Moreover, the window operator has important applications, e.g. in description logics [19].

Due to the usefulness of program negation, it is natural to attempt the identification of fragments of $\mathrm{PDL}^{\neg}$ that still capture some of the desirable properties of program negation, but are well-behaved in a computational sense. One candidate for such a fragment is $\mathrm{PDL}^{\cap}$. As has already been noted, this fragment is indeed decidable, but has a quite intricate model theory. The purpose of this paper is to explore another interesting option: $\mathrm{PDL}^{(\neg)}$, the fragment of $\mathrm{PDL}^{\neg}$ that allows the application of program negation to *atomic* programs, only. Indeed, we show that reasoning in $\mathrm{PDL}^{(\neg)}$ is decidable, and ExpTime-complete—thus not harder than reasoning in PDL itself. Moreover, $\mathrm{PDL}^{(\neg)}$ has a simpler model theory than $\mathrm{PDL}^{\cap}$: we are able to use a decision procedure that is an extension of the standard automata-based decision procedure for PDL [20], and of the standard automata-based decision procedure for Boolean modal logic [21]. Finally, we claim that $\mathrm{PDL}^{(\neg)}$ is still useful for applications: while intersection cannot be expressed any more, the universal modality and the window operator are still available.

To give some more concrete examples of the practicability of $\mathrm{PDL}^{(\neg)}$, let us take a description logic perspective. Description logics are a family of logics that originated in artificial intelligence as a tool for the representation of conceptual knowledge [22]. It is well-known that many description logics (DLs) are notational variants of modal logics [23,9]. In particular, the description logic $\mathcal{ALC}_{\mathrm{reg}}$, which extends the basic DL $\mathcal{ALC}$ with regular expressions on roles, corresponds to PDL [9]. More precisely, DL concepts can be understood as PDL formulas, and DL roles as PDL programs. Thus, the extension $\mathcal{ALC}_{\mathrm{reg}}^{(\neg)}$ of $\mathcal{ALC}_{\mathrm{reg}}$ with negation of atomic (!) roles is a notational variant of $\mathrm{PDL}^{(\neg)}$. We give two examples of knowledge representation with $\mathcal{ALC}_{\mathrm{reg}}^{(\neg)}$. These examples, which use DL syntax rather than PDL syntax, illustrate that the combination of regular expressions on roles and of atomic negation of roles is a very useful one.

1. Some private universities prefer to admit students whose ancestors donated money to the university. Using $\mathcal{ALC}_{\text{reg}}$, the class of all applicants having a donating ancestor can be described with the concept $\exists\mathsf{parent}^{+}.\mathsf{Donator}$. To describe the set of preferred students, we can now combine this concept with the window operator: the $\mathcal{ALC}_{\text{reg}}^{(\neg)}$-concept

$$\mathsf{UniversityX} \rightarrow \forall\mathsf{prefer}.\mathsf{Applicant} \sqcap \forall\neg\mathsf{prefer}.\neg(\exists\mathsf{parent}^{+}.\mathsf{Donator})$$

states that, in the case of University X, only people who actually applied are preferred, and all applicants with donating ancestors are preferred.

2. Suppose that we want to use $\mathcal{ALC}_{\text{reg}}^{(\neg)}$ to talk about trust and mistrust among negotiating parties. Also assume that we have a very strong notion of trust, namely that it is transitive: if I trust x, and x trusts y, then I trust y as well. An analogous assumption for mistrust should clearly not be made. Then, we can model mistrust by using an atomic role $\mathsf{mistrust}$, and trust by using $(\neg\mathsf{mistrust})^{*}$ and say, e.g., that I trust some politicians and never mistrust a family member :

$$\exists(\neg\mathsf{mistrust})^{*}.\mathsf{Politician} \sqcap \forall\mathsf{mistrust}.\neg\mathsf{Familymember}.$$

Note that reversing the roles of trust and mistrust does not work: first, to achieve transitivity of trust, we'd have to introduce an atomic $\mathsf{direct\text{-}trust}$ relation. And second, we could then only speak about the negation of $\mathsf{direct\text{-}trust}$, but not about the negation of $\mathsf{direct\text{-}trust}^{*}$, which corresponds to mistrust.

2 PDL with Negation

In this section, we introduce propositional dynamic logic (PDL) with negation of programs. We start with defining full PDL$^{\neg}$, i.e. PDL extended with negation of (possibly complex) programs. Then, the logics PDL and PDL$^{(\neg)}$, are defined as fragments of PDL$^{\neg}$.

Definition 1 (PDL$^{\neg}$ Syntax). *Let Φ_0 and Π_0 be countably infinite and disjoint sets of* propositional letters *and* atomic programs*, respectively. Then the set $\Pi^{\neg}$ of* PDL$^{\neg}$-programs *and the set $\Phi^{\neg}$ of* PDL$^{\neg}$-formulas *are defined by simultaneous induction, i.e., they are the smallest sets such that:*

- $\Phi_0 \subseteq \Phi^{\neg}$;
- $\Pi_0 \subseteq \Pi^{\neg}$;
- *if* $\varphi, \psi \in \Phi^{\neg}$, *then* $\{\neg\varphi, \varphi \wedge \psi, \varphi \vee \psi\} \subseteq \Phi^{\neg}$;
- *if* $\pi_1, \pi_2 \in \Pi^{\neg}$, *then* $\{\neg\pi_1, \pi_1 \cup \pi_2, \pi_1;\pi_2, \pi_1^{*}\} \subseteq \Pi^{\neg}$;
- *if* $\pi \in \Pi^{\neg}$, *and* $\varphi \in \Phi^{\neg}$, *then* $\{\langle\pi\rangle\varphi, [\pi]\varphi\} \subseteq \Phi^{\neg}$;
- *if* $\varphi \in \Phi^{\neg}$, *then* $\varphi? \in \Pi^{\neg}$

We use $\top$ as abbreviation for an arbitrary propositional tautology, and $\bot$ as abbreviation for $\neg\top$. Moreover, for $\pi, \pi' \in \Pi^{\neg}$ we use $\pi \cap \pi'$ as abbreviation for $\neg(\neg\pi \cup \neg\pi')$.

A formula $\varphi \in \Phi^{\neg}$ is called a PDL$^{(\neg)}$-formula *(*PDL-formula*) if, in φ, negation occurs only in front of atomic programs and formulas (only in front of formulas).*

Throughout this paper, the operator $\langle\pi\rangle$ is called the diamond operator, $[\pi]$ is called the box operator, and programs of the form $\psi?$ are called *tests*. Let us note how formulas of PDL$^\neg$ can be converted into concepts of the description logic $\mathcal{ALC}_{\text{reg}}^{(\neg)}$ mentioned in the introduction: simply replace $\wedge$, $\vee$, $\langle\pi\rangle\psi$, and $[\pi]\psi$ with $\sqcap$, $\sqcup$, $\exists\pi.\psi$, and $\forall\pi.\psi$, respectively.

Definition 2 (PDL$^\neg$ Semantics). *Let $\mathcal{M} = (W, \mathcal{R}, V)$ be a* Kripke structure *where W is the* set of worlds*, $\mathcal{R}$ is a family of* accessibility relations *for atomic programs $\{R_\pi \subseteq W^2 \mid \pi \in \Pi_0\}$, and $V : \Phi_0 \to 2^W$ is a* valuation function*. In the following, we define accessibility relations for compound programs and the satisfaction relation $\models$ by simultaneous induction, where $\cdot^*$ denotes the reflexive-transitive closure:*

$$\begin{array}{rcl}
R_{\varphi?} & := & \{(u,u) \in W^2 \mid \mathcal{M}, u \models \varphi\} \\
R_{\neg\pi} & := & W^2 \backslash R_\pi \\
R_{\pi_1 \cup \pi_2} & := & R_{\pi_1} \cup R_{\pi_2} \\
R_{\pi_1;\pi_2} & := & R_{\pi_1} \circ R_{\pi_2} \\
R_{\pi^*} & := & (R_\pi)^* \\
\mathcal{M}, u \models p & \textit{iff} & u \in V(p) \textit{ for any } p \in \Phi \\
\mathcal{M}, u \models \neg\varphi & \textit{iff} & \mathcal{M}, u \not\models \varphi \\
\mathcal{M}, u \models \varphi_1 \vee \varphi_2 & \textit{iff} & \mathcal{M}, u \models \varphi_1 \textit{ or } \mathcal{M}, u \models \varphi_2 \\
\mathcal{M}, u \models \varphi_1 \wedge \varphi_2 & \textit{iff} & \mathcal{M}, u \models \varphi_1 \textit{ and } \mathcal{M}, u \models \varphi_2 \\
\mathcal{M}, u \models \langle\pi\rangle\varphi & \textit{iff} & \textit{there is a } v \in W \textit{ with } (u,v) \in R_\pi \textit{ and } \mathcal{M}, v \models \varphi \\
\mathcal{M}, u \models [\pi]\varphi & \textit{iff} & \textit{for all } v \in W,\ (u,v) \in R_\pi \textit{ implies } \mathcal{M}, v \models \varphi
\end{array}$$

If $\mathcal{M}, u \models \varphi$ for some formula $\varphi \in \Phi^\neg$ and world $u \in W$, then φ is true *at u in $\mathcal{M}$, and $\mathcal{M}$ is called* model *of φ. A formula is* satisfiable *if it has a model.*

It is well-known that satisfiability of PDL$^\neg$-formulas is undecidable [4]. Since this can be established in a very simple way, we give a proof for illustrative purposes.

The proof is by reduction of the undecidable word-problem for finitely presented semi-groups [24]: given a set of word identities $\{u_1 = v_1, \ldots, u_k = v_k\}$, the task is to decide whether they imply another word identity $u = v$. To reduce this problem to PDL$^\neg$-satisfiability, we need to introduce the universal modality $\Box_U\varphi$, which has the following semantics:

$$\mathcal{M}, u \models \Box_U\varphi \quad \text{iff} \quad \mathcal{M}, v \models \varphi \text{ for all } v \in W.$$

Clearly, in PDL$^\neg$ we can replace $\Box_U\varphi$ with the equivalent $[a]\varphi \wedge [\neg a]\varphi$, where $a \in \Pi_0$ is an arbitrary atomic program. Using the universal modality, the reduction is now easy: we assume that, for every generator of the semi-group, there is an atomic program of the same name, and then note that $\{u_1 = v_1, \ldots, u_k = v_k\}$ implies $u = v$ if and only if the following formula is unsatisfiable:

$$\Big(\langle u \cap \neg v\rangle\top \vee \langle \neg u \cap v\rangle\top\Big) \wedge \Box_U\Big(\bigwedge_{i=1..k} [u_i \cap \neg v_i]\bot \wedge [v_i \cap \neg u_i]\bot\Big).$$

Here, we assume that the symbols of the words u_i and v_i (and of u and v) are separated by program composition ";".

Since PDL$^{\neg}$ is a very useful logic for a large number of purposes, this undecidability result is rather disappointing. As has been argued in the introduction, it is thus a natural idea to search for decidable fragments of PDL$^{\neg}$ that still extend PDL in a useful way. In the remainder of this paper, we will prove that PDL$^{(\neg)}$ is such a fragment. Note that, in PDL$^{(\neg)}$, we can still define the universal modality as described above. Also note that we can use negated atomic programs nested inside other program operators.

3 An Automata-Based Variant of PDL$^{(\neg)}$

Similar to some related results in [20], our decidability proof is based on Büchi-automata on infinite trees. It has turned out that, for such proofs, it is rather convenient to use variants of PDL in which complex programs are described by means of automata on finite words, rather than by regular expressions. Therefore, in this section we define a corresponding variant APDL$^{(\neg)}$ of PDL$^{(\neg)}$.

Definition 3 (Finite automata). *A* (nondeterministic) finite automaton (NFA) $\mathcal{A}$ *is a quintuple* $(Q, \Sigma, q_0, \Delta, F)$ *where*

- Q *is a finite set of* states*,*
- Σ *is a finite* alphabet*,*
- q_0 *is an* initial state*,*
- $\Delta : Q \times \Sigma \to 2^Q$ *is a (partial)* transition function*, and*
- $F \subseteq Q$ *is the set of* accepting states*.*

The function Δ *can be inductively extended to a function from* $Q \times \Sigma^*$ *to* 2^Q *in a natural way:*

- $\Delta(q, \varepsilon) := \{q\}$*, where* ε *is the* empty word*;*
- $\Delta(q, wa) := \{q'' \in Q \mid q'' \in \Delta(q', a)$ *for some* $q' \in \Delta(q, w)\}$*.*

A sequence $p_0, \ldots, p_n \in Q$*,* $n \geq 0$*, is a* run *of* $\mathcal{A}$ *on the word* $a_1 \cdots a_n \in \Sigma^*$ *if* $p_0 = q_0$*,* $p_i \in \Delta(p_{i-1}, a_i)$ *for* $0 < i \leq n$*, and* $p_n \in F$*. A word* $w \in \Sigma^*$ *is* accepted *by* $\mathcal{A}$ *if there exists a run of* $\mathcal{A}$ *on* w*. The* language *accepted by* $\mathcal{A}$ *is the set* $\mathcal{L}(\mathcal{A}) := \{w \in \Sigma^* \mid w$ *is accepted by* $\mathcal{A}\}$*.*

To obtain APDL$^{(\neg)}$ from PDL$^{(\neg)}$, we replace complex programs (i.e. regular expressions) inside boxes and diamonds with automata. For the sake of exactness, we give the complete definition.

Definition 4 (APDL$^{(\neg)}$ Syntax). *The set* $\Pi_0^{(\neg)}$ *of* program literals *is defined as* $\{a, \neg a \mid a \in \Pi_0\}$*. The sets* $A\Pi^{(\neg)}$ *of* program automata *and* $A\Phi^{(\neg)}$ *of* APDL$^{(\neg)}$-formulas *are defined by simultaneous induction, i.e.,* $A\Pi^{(\neg)}$ *and* $A\Phi^{(\neg)}$ *are the smallest sets such that:*

- $\Phi_0 \subseteq A\Phi^{(\neg)}$*;*
- *if* $\varphi, \psi \in A\Phi^{(\neg)}$*, then* $\{\neg\varphi, \varphi \vee \psi, \varphi \wedge \psi\} \subseteq A\Phi^{(\neg)}$*;*
- *if* $\alpha \in A\Pi^{(\neg)}$ *and* $\varphi \in A\Phi^{(\neg)}$*, then* $\{\langle\alpha\rangle\varphi, [\alpha]\varphi\} \subseteq A\Phi^{(\neg)}$*;*

– *if* α *is a finite automaton with alphabet* $\Sigma \subseteq \Pi_0^{(\neg)} \cup \{\psi? \mid \psi \in A\Phi^{(\neg)}\}$, *then* $\alpha \in A\Pi^{(\neg)}$

Note that the alphabet of program automata is composed of atomic programs, of negated atomic programs, and of tests.

Definition 5 (APDL$^{(\neg)}$ Semantics). *Let* $\mathcal{M} = (W, \mathcal{R}, V)$ *be a Kripke structure as in Definition 2. We inductively define a relation* R *mapping each program literal, each test, and each program automaton to a binary relation over* W. *This is done simultaneously with the definition of the satisfaction relation* $\models$:

$$
\begin{array}{rcl}
R(a) & := & R_a \textit{ for each } a \in \Pi_0 \\
R(\neg a) & := & W^2 \setminus R_a \textit{ for each } a \in \Pi_0 \\
R(\psi?) & := & \{(u,u) \in W^2 \mid \mathcal{M}, u \models \psi\} \\
R(\alpha) & := & \{(u,v) \in W^2 \mid \textit{there is a word } w = w_1 \cdots w_m \in \mathcal{L}(\alpha), \\
 & & m \geq 0, \textit{ and worlds } u_0, \ldots, u_m \in W \textit{ such that} \\
 & & u = u_0 R(w_1) u_1 R(w_2) \cdots u_{m-1} R(w_m) u_m = v\} \\
\mathcal{M}, u \models p & \textit{iff} & u \in V(p) \textit{ for any } p \in \Phi, \\
\mathcal{M}, u \models \neg\varphi & \textit{iff} & \mathcal{M}, u \not\models \varphi, \\
\mathcal{M}, u \models \varphi_1 \vee \varphi_2 & \textit{iff} & \mathcal{M}, u \models \varphi_1 \textit{ or } \mathcal{M}, u \models \varphi_2, \\
\mathcal{M}, u \models \varphi_1 \wedge \varphi_2 & \textit{iff} & \mathcal{M}, u \models \varphi_1 \textit{ and } \mathcal{M}, u \models \varphi_2, \\
\mathcal{M}, u \models \langle\alpha\rangle\varphi & \textit{iff} & \textit{there is a } u' \in W \textit{ with } (u,u') \in R(\alpha) \textit{ and } \mathcal{M}, u' \models \varphi, \\
\mathcal{M}, u \models [\alpha]\varphi & \textit{iff} & \textit{for all } u' \in W, (u,u') \in R(\alpha) \textit{ implies } \mathcal{M}, u' \models \varphi.
\end{array}
$$

Since every language defined by a regular expression can also be accepted by a finite automaton and vice versa [25], it is straightforward to verify that PDL$^{(\neg)}$ and APDL$^{(\neg)}$ have the same expressive power. Moreover, upper complexity bounds carry over from APDL$^{(\neg)}$ to PDL$^{(\neg)}$ since conversion of regular expressions to finite automata can be done with at most a polynomial blow-up in size (the converse does not hold true).

It is interesting to note that, in many automata-based decision procedures for variants of PDL, a *deterministic* version of APDL is used, i.e. a variant of APDL in which there may be at most one successor for each world and each atomic program [20]. In a second step, satisfiability in the non-deterministic APDL-variant is then reduced to satisfiability in the deterministic one. We cannot take this approach here since we cannot w.l.o.g. assume that both atomic programs *and their negations* are deterministic. Indeed, this would correspond to limiting the size of Kripke structures to only two worlds.

4 Hintikka-Trees

This section provides a core step toward using Büchi-tree automata for deciding the satisfiability of APDL$^{(\neg)}$-formulas. The intuition behind this approach is as follows: to decide the satisfiability of an APDL$^{(\neg)}$-formula φ, we translate it into a Büchi-tree automaton $\mathcal{B}_\varphi$ such that the trees accepted by the automaton correspond in some way to models of the formula φ. To decide satisfiability of

φ, it then remains to perform a simple emptiness-test on the automaton $\mathcal{B}_\varphi$: the accepted language will be non-empty if and only if φ has a model.

In the case of APDL$^{(\neg)}$, one obstacle to this approach is that APDL$^{(\neg)}$ does not enjoy the *tree model property (TMP)*, i.e., there are APDL$^{(\neg)}$-formulas that are satisfiable only in non-tree models. For example, for each $n \in \mathbb{N}$ the following PDL$^{(\neg)}$-formula enforces a cycle of length n:

$$\psi_1^n \wedge \langle a \rangle(\psi_2^n \wedge \langle a \rangle(\cdots(\psi_n^n \wedge [\neg a]\neg\psi_1^n)\cdots)),$$

where, for $1 \leq i \leq n$, $\psi_i^n = p_1 \wedge \cdots \wedge \neg p_i \wedge \cdots \wedge p_n$ with propositional variables $p_1, \ldots, p_n$. Note that the formula inside the diamond simulates the window operator and in this way closes the cycle. Thus, we have to invest some work to obtain tree-shaped representations of (possibly non-tree) models that can then be accepted by Büchi-automata.

As a preliminary, we assume that all APDL$^{(\neg)}$-formulas are in *negation normal form (NNF)*, i.e. that negation occurs only in front of propositional letters. This assumption can be made w.l.o.g. since each formula can be converted into an equivalent one in NNF by exhaustively eliminating double negation, applying DeMorgan's rules, and exploiting the duality between diamonds and boxes. For the sake of brevity, we introduce the following notational conventions:

- for each $APDL^{(\neg)}$-formula φ, $\dot{\neg}\varphi$ denotes the NNF of $\neg\varphi$;
- for each program literal π, $\overline{\pi}$ denotes $\neg\pi$ if π is an atomic program, and a if $\pi = \neg a$ for some atomic program a;
- for each program automaton α, we use Q_α, Σ_α, q_α, Δ_α, and F_α to denote the components of $\alpha = (Q, \Sigma, q_0, \Delta, F)$;
- for each program automaton α and state $q \in Q_\alpha$, we use α_q to denote the automaton $(Q_\alpha, \Sigma_\alpha, q, \Delta_\alpha, F_\alpha)$, i.e. the automaton obtained from α by using q as the new initial state.

Before we can develop the tree-shaped abstraction of models, we need to fix a *closure*, i.e. a set of formulas $\mathsf{cl}(\varphi)$ relevant for deciding the satisfiability of an input formula φ. This is done analogous to [3,20]. In the following, when we talk of a subformula ψ of a formula φ, we mean that ψ can be obtained from φ by decomposing only formula operators, but not program operators. For example, a is a subformula of $\langle b? \rangle a$, while b is not.

Definition 6 (Closure). *Let φ be a $APDL^{(\neg)}$-formula. The set $\mathsf{cl}(\varphi)$ is the smallest set which is closed under the following conditions:*

(C1) $\varphi \in \mathsf{cl}(\varphi)$

(C2) if ψ is a subformula of $\psi' \in \mathsf{cl}(\varphi)$, then $\psi \in \mathsf{cl}(\varphi)$

(C3) if $\psi \in \mathsf{cl}(\varphi)$, then $\dot{\neg}\psi \in \mathsf{cl}(\varphi)$

(C4) if $\langle \alpha \rangle \psi \in \mathsf{cl}(\varphi)$, then $\psi' \in \mathsf{cl}(\varphi)$ for all $\psi'? \in \Sigma_\alpha$

(C5) if $\langle \alpha \rangle \psi \in \mathsf{cl}(\varphi)$, then $\langle \alpha_q \rangle \psi \in \mathsf{cl}(\varphi)$ for all $q \in Q_\alpha$

(C6) if $[\alpha]\psi \in \mathsf{cl}(\varphi)$, then $\psi' \in \mathsf{cl}(\varphi)$ for all $\psi'? \in \Sigma_\alpha$

(C7) if $[\alpha]\psi \in \mathsf{cl}(\varphi)$, then $[\alpha_q]\psi \in \mathsf{cl}(\varphi)$ for all $q \in Q_\alpha$

It is standard to verify that the cardinality of $\mathsf{cl}(\varphi)$ is polynomial in the length of φ, see e.g. [5]. We generally assume the diamond formulas (i.e. formulas of the form $\langle\alpha\rangle\psi$) in $\mathsf{cl}(\varphi)$ to be linearly ordered and use ϵ_i to denote the i-th diamond formula in $\mathsf{cl}(\varphi)$, with ϵ_1 being the first one. Note that a changed initial state of an automaton results in a different diamond formula.

To define *Hintikka-trees*, the tree-shaped abstraction of models underlying our decision procedure, we proceed in three steps. First, we introduce *Hintikka-sets* that will be used as (parts of) node labels. Intuitively, each node in the tree describes a world of the corresponding model, and its label contains the formulas from the closure of the input formula φ that are true in this world. Second, we introduce a *matching relation* that describes the possible "neighborhoods" that we may find in Hintikka-trees, where a neighborhood consists of a labeled node and its labeled successors. And third, we use these ingredients to define Hintikka-trees.

Definition 7 (Hintikka-set). *Let $\psi \in \Phi^{(\neg)}$ be an APDL$^{(\neg)}$-formula, and $\alpha \in \Pi^{(\neg)}$ a program automaton. The set $\Psi \subseteq \mathsf{cl}(\varphi)$ is a* Hintikka-set for φ *if*

(H1) if $\psi_1 \wedge \psi_2 \in \Psi$, then $\psi_1 \in \Psi$ and $\psi_2 \in \Psi$

(H2) if $\psi_1 \vee \psi_2 \in \Psi$, then $\psi_1 \in \Psi$ or $\psi_2 \in \Psi$

(H3) $\psi \in \Psi$ iff $\dot{\neg}\psi \notin \Psi$

(H4) if $[\alpha]\psi \in \Psi$ and $q_\alpha \in F_\alpha$, then $\psi \in \Psi$

(H5) if $[\alpha]\psi \in \Psi$ then, for any state $q \in Q_\alpha$ and test $\theta? \in \Sigma_\alpha$,
$q \in \Delta_\alpha(q_\alpha, \theta?)$ implies that $\dot{\neg}\theta \in \Psi$ or $[\alpha_q]\psi \in \Psi$

The set of all Hintikka-sets for φ is designated by $\mathcal{H}_\varphi$.

The conditions (H1) to (H3) are standard, with one exception: (H3) is stronger than usual since it enforces maximality of Hintikka-sets by stating that, for each formula $\psi \in \mathsf{cl}(\varphi)$, either ψ or $\dot{\neg}\psi$ must be in the Hintikka-set. This will be used later on to deal with negated programs. The last two conditions (H4) and (H5) deal with the "local" impact of box formulas.

Next, we define the matching relation. The purpose of this relation can be understood as follows: in the Hintikka-tree, each node has exactly one successor for every diamond formula in $\mathsf{cl}(\varphi)$. The matching relation helps to ensure that all diamond formulas in a node's label can be satisfied "via" the corresponding successor in the Hintikka-tree, and that none of the box formulas is violated via any successors. We talk of "via" here since going to an immediate successor corresponds to travelling along a *single* program literal. Since programs in APDL$^{(\neg)}$ are automata that may only accept words of length greater one, in general we cannot satisfy diamonds by going only to the immediate successor, but rather we must perform a sequence of such moves.

Before we define the matching relation formally, let us fix the structure of node labels of Hintikka-trees. For reasons that will be discussed below, node labels not only contain a Hintikka-set, but also two additional components. More

precisely, if φ is an APDL$^{(\neg)}$-formula and $\mathsf{cl}(\varphi)$ contains k diamond formulas, then we use

- $\Pi_\varphi^{(\neg)}$ to denote the set of all program literals occurring in φ; and
- Λ_φ to abbreviate $\mathcal{H}_\varphi \times (\Pi_\varphi^{(\neg)} \cup \{\bot\}) \times \{0, \ldots, k\}$, i.e. the set of triples containing a Hintikka-set for φ, a program literal of φ or $\bot$, and a number at most k.

The elements of Λ_φ will be used as node labels in Hintikka-trees. Intuitively, the first component lists the formulas that are true at a node, the second component fixes the program literal with which the node can be reached from its predecessor (or $\bot$ if this information is not important), and the third component will help to ensure that diamond formulas are eventually satisfied when moving through the tree. For a triple $\lambda \in \Lambda_\varphi$, we refer to the first, second and third triple component with λ^1, λ^2, and λ^3, respectively. For the following definition, recall that we use ϵ_i to denote the i-th diamond in $\mathsf{cl}(\varphi)$.

Definition 8 (Matching). *Let φ be a formula and k the number of diamond formulas in $\mathsf{cl}(\varphi)$. A $k+1$-tuple of Λ_φ-triples $(\lambda, \lambda_1, \ldots, \lambda_k)$ is* matching *if, for $1 \leq i \leq k$ and all automata $\alpha \in A\Pi^{(\neg)}$, the following holds:*

(M1) if $\epsilon_i = \langle\alpha\rangle\psi \in \lambda^1$, then there is a word $w = \psi_1? \cdots \psi_n? \in \Sigma_\alpha^*$, $n \geq 0$, and a state $q_1 \in Q_\alpha$ such that $\{\psi_1, \ldots, \psi_n\} \subseteq \lambda^1$, $q_1 \in \Delta_\alpha(q_\alpha, w)$, and one of the following holds:

(a) q_1 is a final state, $\psi \in \lambda^1$, $\lambda_i^2 = \bot$, and $\lambda_i^3 = 0$

(b) there is a program literal $\pi \in \Sigma_\alpha$ and a state $q_2 \in Q_\alpha$ such that

$$q_2 \in \Delta_\alpha(q_1, \pi),\ \epsilon_j = \langle\alpha_{q_2}\rangle\psi \in \lambda_i^1,\ \lambda_i^2 = \pi, \text{ and } \lambda_i^3 = j.$$

(M2) if $[\alpha]\psi \in \lambda^1$, $q \in Q_\alpha$, and $\pi \in \Sigma_\alpha$ a program literal such that $q \in \Delta_\alpha(q_\alpha, \pi)$, then $\pi = \lambda_i^2$ implies $[\alpha_q]\psi \in \lambda_i^1$.

As already noted, the purpose of the matching relation is to describe the possible neighborhoods in Hintikka-trees. To this end, think of λ as the label of a node, and of $\lambda_1, \ldots, \lambda_k$ as the labels of its successors. The purpose of Conditions (M1) and (M2) is to ensure that diamonds are satisfied and that boxes are not violated, respectively. Let us consider only (M1). If a diamond $\epsilon_i = \langle\alpha\rangle\psi$ is in the first component of λ, it can either be satisfied in the node labeled with λ itself (Condition (a)) or we can "delay" its satisfaction to the i-th successor node that is reserved specifically for this purpose (Condition (b)). In Case (a), it is not important over which program literal we can reach the i-th successor, and thus the second component of λ_i can be set to $\bot$. In the second case, we must choose a suitable program literal π and a suitable state q of α, make sure that the i-th successor is reachable over π via its second λ_i-component, and guarantee that the first component of λ_i contains the diamond under consideration with the automata α "advanced" to initial state q.

The remaining building block for ensuring that diamonds are satisfied is to enforce that the satisfaction of diamonds is not delayed forever. This is one of

the two core parts of the definition of Hintikka-trees, the other being the proper treatment of negation. Before we can discuss the prevention of infinitely delayed diamonds in some more detail, we have to introduce some basic notions.

Let M be a set and $k \in \mathbb{N}$. An *(infinite) k-ary M-tree* T is a mapping $T : [k]^* \to M$, where $[k]$ is used (now and in the following) as an abbreviation for the set $\{1, \ldots, k\}$. Intuitively, the node αi is the i-th child of α. We use ε to denote the empty word (corresponding to the root of the tree). An infinite *path* in a k-ary M-tree is an infinite word γ over the alphabet $[k]$. We use $\gamma[n]$, $n \geq 0$, to denote the prefix of γ up to the n-th element of the sequence (with $\gamma[0]$ yielding the empty sequence).

Now back to the prevention of infinitely delayed diamonds. Given a formula φ with k diamond formulas in $\mathsf{cl}(\varphi)$, a Hintikka-tree will be defined as a k-ary Λ_φ-tree in which every neighborhood is matching and some additional conditions are satisfied. To detect infinite delays of diamonds in such trees, it does *not* suffice to simply look for infinite sequences of nodes that all contain the same diamond: firstly, diamonds are evolving while being "pushed" through the tree since their initial state might be changed. Secondly, such a sequence does not necessarily correspond to an infinite delay of diamond satisfaction: it could as well be the case that the diamond is satisfied an infinite number of times, but always immediately "regenerated" by some other formula. Also note that we cannot use the standard technique from [20] since it only works for deterministic variants of PDL.

Precisely for this purpose, the easy detection of infinitely delayed diamonds, we have introduced the third component of node labels in Hintikka trees: if a diamond was pushed to the current node x from its predecessor, then by (M1) the third component of x's label contains the number of the pushed diamond. Moreover, if the pushed diamond is not satisfied in x, we again use the third component of x: it contains the number of the successor of x to which the diamond's satisfaction is (further) delayed. If no diamond was pushed to x, its third component is simply zero. Thus, the following definition captures our intuitive notion of infinitely delayed diamonds.

Definition 9 (Diamond Starvation). *Let φ be an APDL$^{(\neg)}$-formula with k diamond formulas in $\mathsf{cl}(\varphi)$, T a k-ary Λ_φ-tree, $x \in [k]^*$ a node in T, and $\epsilon_i = \langle\alpha\rangle\psi \in T(x)^1$. Then the diamond formula $\langle\alpha\rangle\psi$ is called* starving in x *if there exists a path $\gamma = \gamma_1\gamma_2 \cdots \in [k]^\omega$ such that*

1. $\gamma_1 = i$,
2. $T(x\gamma[n])^3 = \gamma_{n+1}$ *for* $n \geq 1$.

We have now gathered all ingredients to define Hintikka-trees formally.

Definition 10 (Hintikka-tree). *Let φ be an APDL$^{(\neg)}$-formula with k diamond formulas in $\mathsf{cl}(\varphi)$. A k-ary Λ_φ-tree T is a* Hintikka-tree for φ *if T satisfies,*

for all nodes $x, y \in [k]^*$, the following conditions:

(T1) $\varphi \in T(\varepsilon)^1$

(T2) the $k+1$*-tuple* $(T(x), T(x1), \ldots, T(xk))$ *is matching*

(T3) no diamond formula from $\mathsf{cl}(\varphi)$ *is starving in* x

(T4) if $[\alpha]\psi, [\beta]\theta \in T(x)^1$, $\pi \in \Pi_0^{(\neg)}$, $q'_\alpha \in Q_\alpha$, *and* $q'_\beta \in Q_\beta$ *such that* $q'_\alpha \in \Delta_\alpha(q_\alpha, \pi)$ *and* $q'_\beta \in \Delta_\beta(q_\beta, \overline{\pi})$, *then* $[\alpha_{q'_\alpha}]\psi \notin T(y)^1$ *implies* $[\beta_{q'_\beta}]\theta \in T(y)^1$.

Conditions (T1) to (T3) are easily understood. The purpose of Condition (T4) is to deal with negated programs. In particular, for each atomic program a we have to ensure that any pair of nodes x, y of a Hintikka-tree T can be related by one of a and $\neg a$ without violating any boxes. This is done by (T4) together with (H3)—indeed, this is the reason for formulating (H3) stronger than usual. Intuitively, the treatment of negation can be understood as follows: suppose that $[\alpha]\psi \in T(x)^1$, let $q \in \Delta_\alpha(q_\alpha, a)$ for some atomic program a, and let y be a node. By (H3), we have either $[\alpha_q]\psi \in T(y)^1$ or $\dot{\neg}[\alpha_q]\psi \in T(y)^1$. In the first case, x and y can be related by a. In the second case, (T4) ensures that they can be related by $\neg a$. This technique is inspired by [21], but generalized to program automata.

The following proposition shows that Hintikka-trees are indeed proper abstractions of models. A proof can be found in [26].

Proposition 1. *An APDL$^{(\neg)}$-formula φ is satisfiable iff it has a Hintikka-tree.*

5 Büchi Automata for Hintikka-Trees

In this section, we show that it is possible to construct, for every APDL$^{(\neg)}$-formula φ, a Büchi tree automaton $\mathcal{B}_\varphi$ that accepts exactly the Hintikka-trees for φ. By Proposition 1, since the size of $\mathcal{B}_\varphi$ is at most exponential in the length of φ, and since the emptiness of Büchi-tree automata can be verified in quadratic time [20], this yields an ExpTime decision procedure for the satisfiability of APDL$^{(\neg)}$-formulas. We start with introducing Büchi tree automata.

Definition 11 (Büchi Tree Automaton). *A* Büchi tree automaton $\mathcal{B}$ for k-ary M-trees *is a quintuple* (Q, M, I, Δ, F), *where*

- Q *is a finite set of* states,
- M *is a finite* alphabet,
- $I \subseteq Q$ *is the set of* initial states,
- $\Delta \subseteq Q \times M \times Q^k$ *is the* transition relation, *and*
- $F \subseteq Q$ *is the set of* accepting states.

Let M be a set of labels, and T a k-ary M-tree. Then, a run *of $\mathcal{B}$ on T is a k-ary Q-tree r such that*

1. $r(\varepsilon) \in I$, *and*
2. $(r(x), T(x), r(x1), \ldots, r(xk)) \in \Delta$ *for all nodes* $x \in [k]^*$.

Let $\gamma \in [k]^\omega$ *be a path. The set* $inf_r(\gamma)$ *contains the states in* Q *that occur infinitely often in run* r *along path* γ. *A run* r *of* $\mathcal{B}$ *on* T *is* accepting *if, for each path* $\gamma \in [k]^\omega$, *we have* $inf_r(\gamma) \cap F \neq \emptyset$. *The* language *accepted by* $\mathcal{B}$ *is the set* $\mathcal{L}(\mathcal{B}) = \{T \mid$ *there is an accepting run of* $\mathcal{B}$ *on* $T\}$.

Given a Büchi automaton $\mathcal{B}$, the problem whether its language is empty, i.e., whether it holds that $\mathcal{L}(\mathcal{B}) = \emptyset$, is called the *emptiness problem*. This problem is solvable in time quadratic in the size of the automaton [20].

We now give the translation of APDL$^{(\neg)}$-formulas φ into Büchi-automata $\mathcal{B}_\varphi$. To simplify the notation, we write $\mathcal{P}_\Box(\varphi)$ to denote the set of sets $\{\{[\alpha]\psi, [\beta]\theta\} \mid [\alpha]\psi, [\beta]\theta \in \mathsf{cl}(\varphi)\}$. We first introduce our automata formally and then explain the intuition.

Definition 12. *Let* φ *be an APDL*$^{(\neg)}$*-formula with* $\mathsf{cl}(\varphi)$ *containing* k *diamond formulas. The Büchi tree automaton* $\mathcal{B}_\varphi = (Q, \Lambda_\varphi, I, \Delta, F)$ *on* k*-ary* Λ_φ*-trees is defined as follows:*

- Q *contains those triples* $((\Psi, \pi, \ell), P, d) \in \Lambda_\varphi \times 2^{\mathcal{P}_\Box(\varphi)} \times \{\oslash, \uparrow\}$ *that satisfy the following conditions:*
  (1) if $\{[\alpha]\psi, [\beta]\theta\} \subseteq \Psi$, *then* $\{[\alpha]\psi, [\beta]\theta\} \in P$
  (2) if $\{[\alpha]\psi, [\beta]\theta\} \in P$, $\pi \in \Pi^{(\neg)}$, $q'_\alpha \in \Delta_\alpha(q_\alpha, \pi)$, $q'_\beta \in \Delta_\beta(q_\beta, \overline{\pi})$, *and* $[\alpha_{q'_\alpha}]\psi \notin \Psi$, *then* $[\beta_{q'_\beta}]\theta \in \Psi$
- $I := \{((\Psi, \pi, \ell), P, d) \in Q \mid \varphi \in \Psi$, *and* $d = \oslash\}$.
- $((\lambda_0, P_0, d_0), (\Psi, \pi, \ell), (\lambda_1, P_1, d_1), \ldots, (\lambda_k, P_k, d_k)) \in \Delta$ *if and only if, for each* $i \in [k]$, *the following holds:*
  1. $\lambda_0 = (\Psi, \pi, \ell)$,
  2. $P_0 = P_i$,
  3. *the tuple* $(\lambda_0, \ldots, \lambda_k)$ *is matching,*
  4. $d_i = \begin{cases} \uparrow & \text{if } d_0 = \oslash,\ \lambda_i^3 \neq 0 \text{ and } \epsilon_i \in \Psi \\ \uparrow & \text{if } d_0 = \uparrow,\ \lambda_0^3 = i, \text{ and } \lambda_i^3 \neq 0 \\ \oslash & \text{otherwise.} \end{cases}$
- *The set* F *of accepting states is* $F := \{(\lambda, P, d) \in Q \mid d = \oslash\}$.

While it is not hard to see how the set of initial states enforces (T1) of Hintikka-trees and how the transition relation enforces (T2), Conditions (T3) and (T4) are more challenging. In the following, we discuss them in detail.

Condition (T3) is enforced with the help of the third component of states, which may take the values "$\oslash$" and "$\uparrow$". Intuitively, the fourth point in the definition of Δ ensures that, whenever the satisfaction of a diamond is delayed in a node x and r is a run, then r assigns states with third component $\uparrow$ to all nodes on the path that "tracks" the diamond delay. Note that, for this purpose, the definition of Δ refers to the third component of Λ_φ-tuples, which is "controlled"

by (M1) in the appropriate way. All nodes that do not appear on delayed diamond paths are labeled with $\oslash$. Then, the set of accepting states ensures that there is no path that, from some point on, is constantly labeled with $\uparrow$. Thus, we enforce that no diamonds are delayed infinitely in trees accepted by our automata, i.e. no starvation occurs.

There is one special case that should be mentioned. Assume that a node x contains a diamond $\epsilon_i = \langle\alpha\rangle\psi$ that is not satisfied "within this node" (Case (a) of (M1) does not apply). Then there is a potential starvation path for ϵ_i that starts at x and goes through the node xi: (M1) "advances" the automaton α to α_q, and ensures that $\epsilon_j = \langle\alpha_q\rangle\psi \in T(xi)^1$ and that $T(xi)^3 = j$. Now suppose that $T(xi)^1$ contains another diamond $\epsilon_k = \langle\beta\rangle\theta$ with $\epsilon_j \neq \epsilon_k$. If ϵ_k is not satisfied within xi, there is a potential starvation path for ϵ_k starting at xi and going through xik. Since the starvation path for ϵ_i and the starvation path for ϵ_k are for different diamonds, we must be careful to separate them—failure in doing this would result in some starvation-free Hintikka-trees to be rejected. Thus, the definition of Δ ensures that runs label xik with $\oslash$, and the constant $\uparrow$-labeling of the starvation path for ϵ_k is delayed by one node: it starts only at the *successor* of xik on the starvation path for ϵ_k.

Now for Condition (T4). In contrast to Conditions (T1) and (T2), this condition has a global flavor in the sense that it does not only concern a node and its successors. Thus, we need to employ a special technique to enforce that (T4) is satisfied: we use the second component of states as a "bookkeeping component" that allows to propagate global information. More precisely, Point (1) of the definition of Q and Point (1) of the definition of Δ ensure that, whenever two boxes appear in a Hintikka-set labeling a node x in a Hintikka-tree T, then this joint occurrence is recorded in the second component of the state that any run assigns to x. Via the definition of the transition relation (second point), we further ensure that all states appearing in a run share the same second component. Thus, we may use Point (2) of the definition of Q and Point (1) of the definition of Δ to ensure that any node y satisfies the property stated by Condition (T4).

The following proposition shows that the Büchi tree automaton $\mathcal{B}_\varphi$ indeed accepts precisely the Hintikka-trees for APDL$^{(\neg)}$-formula φ. A proof can be found in [26].

Proposition 2. *Let φ be an APDL$^{(\neg)}$-formula and T a k-ary Λ_φ-tree. Then T is a Hintikka-tree for φ iff $T \in \mathcal{L}(\mathcal{B}_\varphi)$.*

Putting together Propositions 1 and 2, it is now easy to establish decidability and ExpTime-complexity of APDL$^{(\neg)}$ and thus also of PDL$^{(\neg)}$.

Theorem 1. *Satisfiability of PDL$^{(\neg)}$-formulas is* ExpTime*-complete.*

Proof. From Propositions 1 and 2, it follows that an APDL$^{(\neg)}$-formula φ is satisfiable if and only if $\mathcal{L}(\mathcal{B}_\varphi) \neq \emptyset$. The emptiness problem for Büchi automata is decidable in time quadratic in the size of the automaton [20]. To show that APDL$^{(\neg)}$-formula satisfiability is in ExpTime, it thus remains to show that the size of $\mathcal{B}_\varphi = (Q, \Lambda_\varphi, I, \Delta, F)$ is at most exponential in φ.

Let n be the length of φ. Since the cardinality of $\mathsf{cl}(\varphi)$ is polynomial in n, the cardinality of $\mathcal{H}_\varphi$ (the set of Hintikka-sets for φ) is at most exponential in n. Thus, it is readily checked that the same holds for Λ_Φ and Q. The exponential upper bound on the cardinalities of I and F is trivial. It remains to determine the size of Δ: since the size of Q is exponential in n and the out-degree of trees accepted by automata is polynomial in n, we obtain an exponential bound.

Thus, APDL$^{(\neg)}$-formula satisfiability and hence also PDL$^{(\neg)}$-formula satisfiability are in ExpTime. For the lower bound, it suffices to recall that PDL-formula satisfiability is already ExpTime-hard [3]. □

6 Conclusion

This paper introduces the propositional dynamic logic PDL$^{(\neg)}$, which extends standard PDL with negation of atomic programs. We were able to show that this logic extends PDL in an interesting and useful way, yet retaining its appealing computational properties. There are some natural directions for future work. For instance, it should be simple to further extend PDL$^{(\neg)}$ with the converse operator without destroying the ExpTime upper bound. It would be more interesting, however, to investigate the interplay between (full) negation and PDL's program operators in some more detail. For example, to the best our our knowledge it is unknown whether the fragment of PDL$^{\neg}$ that has only the program operators "$\neg$" and ";" is decidable.

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